

In order to analyse the dynamics of recurrent spiking networks theoretically, one considers homogeneous populations of LIF- or SRM neurons.

For an external input  $I^{ext}(t)$ , one wants to know the population activity

$$A(t) = \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} \frac{n_{act}(t; t + \Delta t)}{N} = \frac{1}{N} \sum_{j=1}^N \sum_f \delta(t - t_j^{(f)}).$$

One can show:

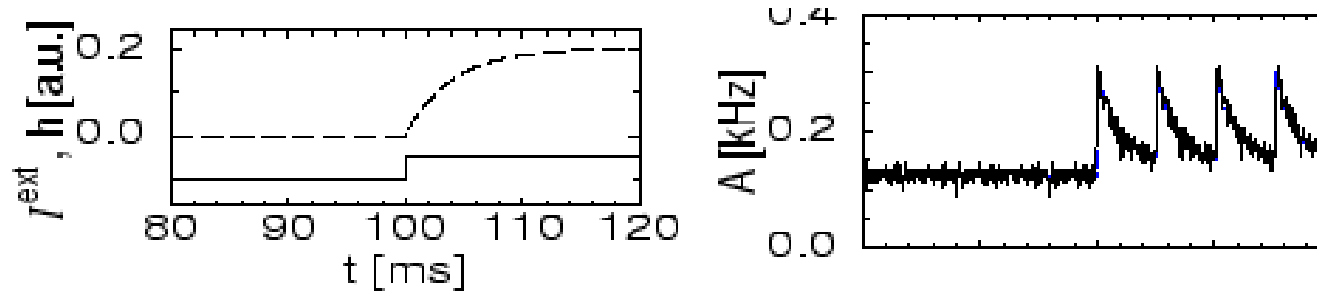
$$A(t) = \int_{-\infty}^t P_I(t|\hat{t}) A(\hat{t}) d\hat{t},$$

where  $P_I(t|\hat{t})$  is the interval distribution of a neuron for input  $I$  given that the last action potential of the neuron was at time  $\hat{t}$ .

$P_I(t|\hat{t})$  depends on the external input, recurrent activity, and from the noise model.

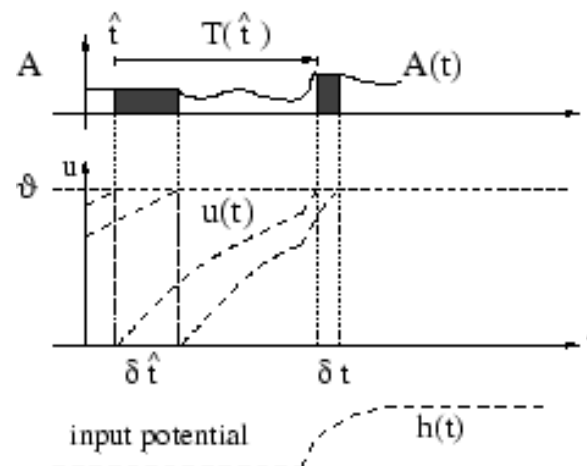
For a given population of uncoupled (i.e., not connected) neurons, the response to a step input depends on the noise level

## Low noise (I&F):

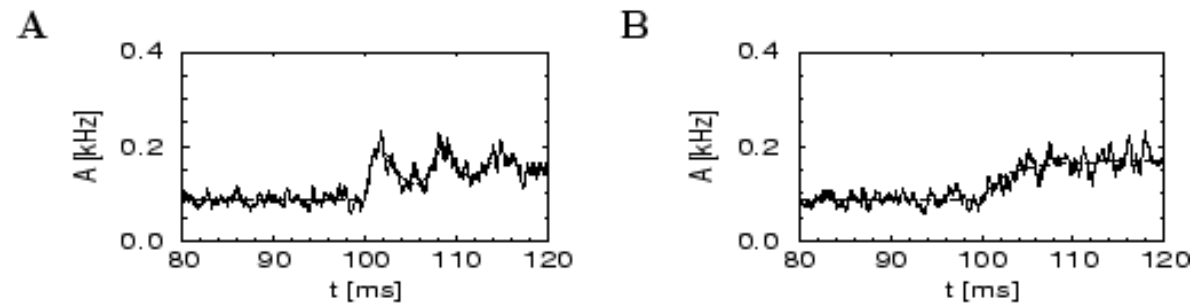


The first activity transient is proportional to the *temporal change* of the membrane potential

$$h(t) = \int_0^\infty \kappa_0(s) I^{ext}(t - s).$$



More noise (A) and high noise (B):



For high noise, the response is proportional to the membrane potential.

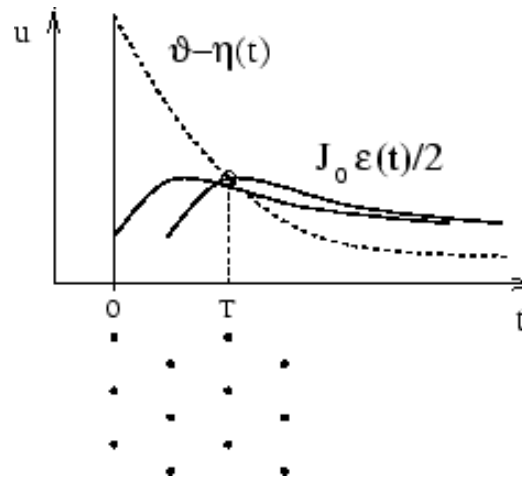
(The noise model used here was white noise on the input current.)

Coupled neural populations tend to oscillate. Whether oscillations occur depends on the synaptic delay and on the noise level.

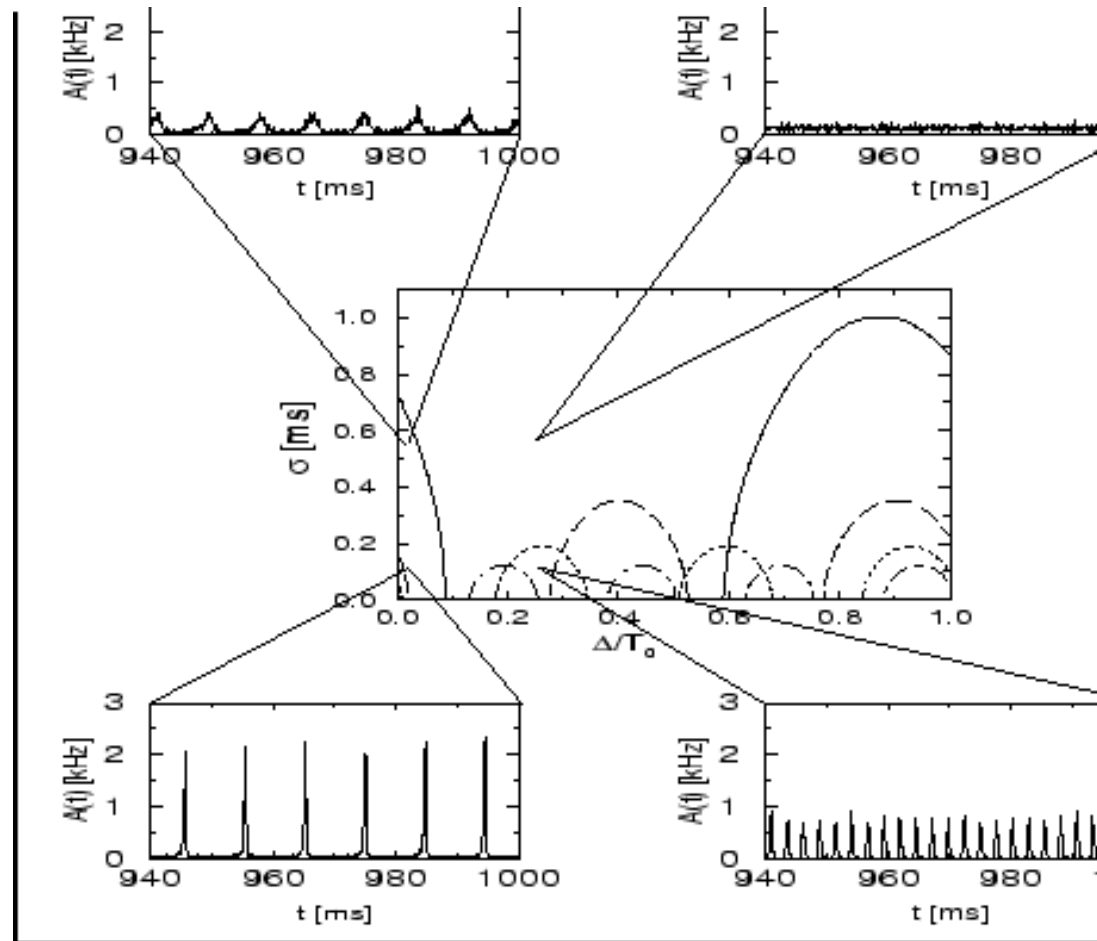
**Asynchronous Regime:** Neurons are firing asynchronous. This regime is only stable for high noise levels.

**Locking:** All neurons are firing together. Can be a stable state without noise.

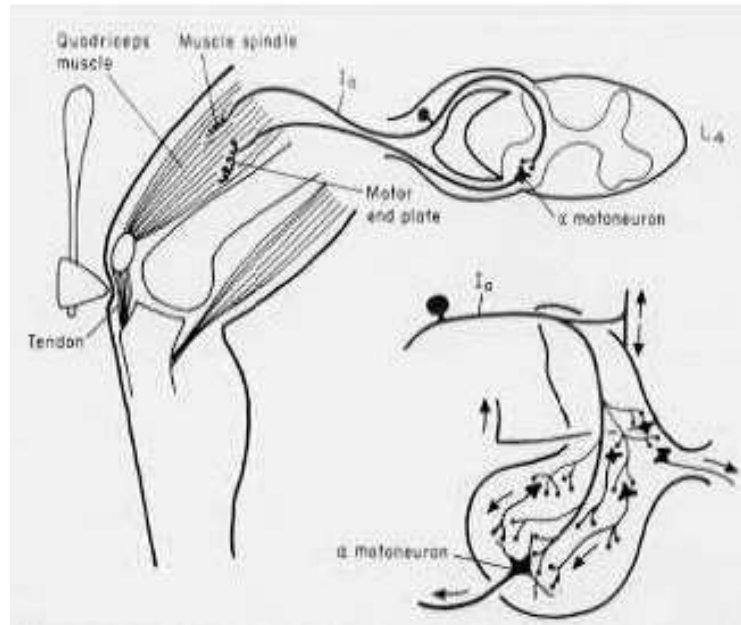
**Cluster states:** Neurons divide into subgroups which fire synchronous. Neurons in each group fire synchronous and trigger the spikes of other groups.



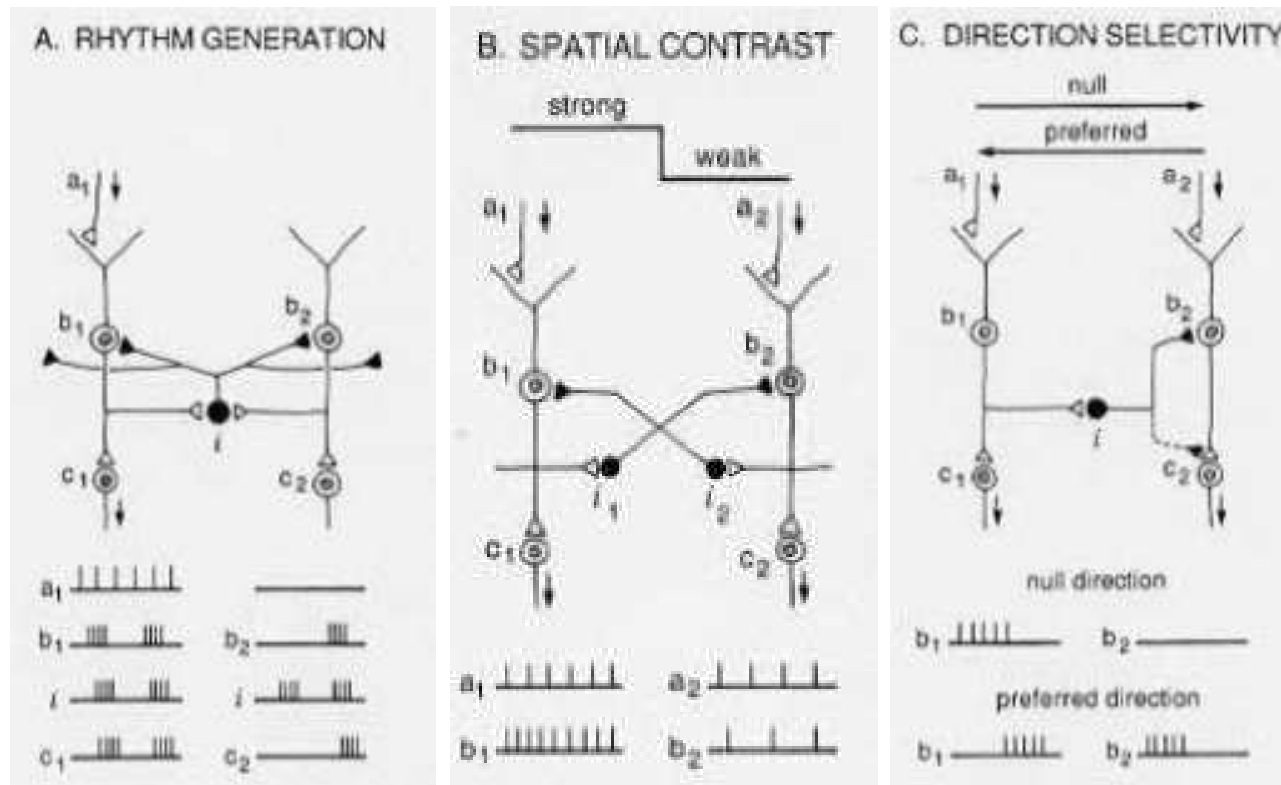
## Stability diagram:



$\Delta$  is the synaptic delay,  $T_0$  is the average inter spike interval,  $\sigma$  is the noise level.



- One of the simplest circuits is the circuit for the knee-reflex.
- An excitatory neuron ( $I_a$ ) projects to a motoneuron.
- If the muscle is strongly stretched, it is contracted due to the motoneuron.
- Reciprocal inhibition:  $I_a$  inhibits also the antagonist via an inhibitory neuron.

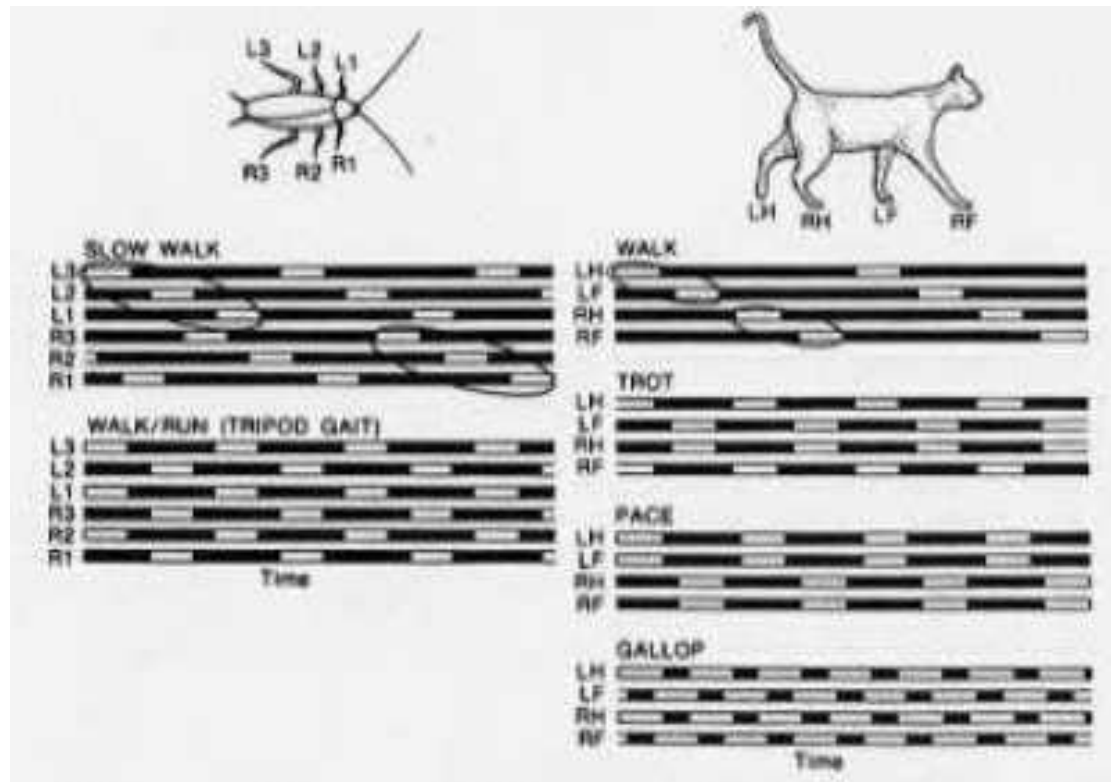


**A** Oscillator

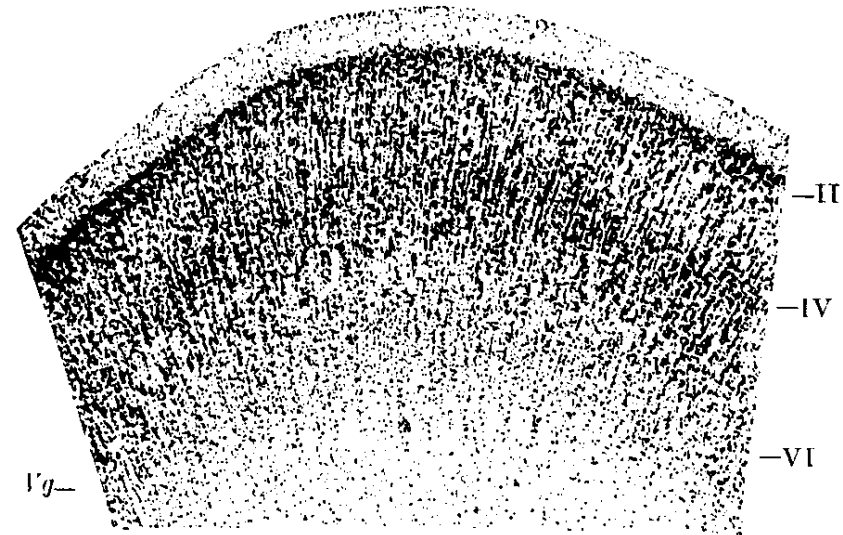
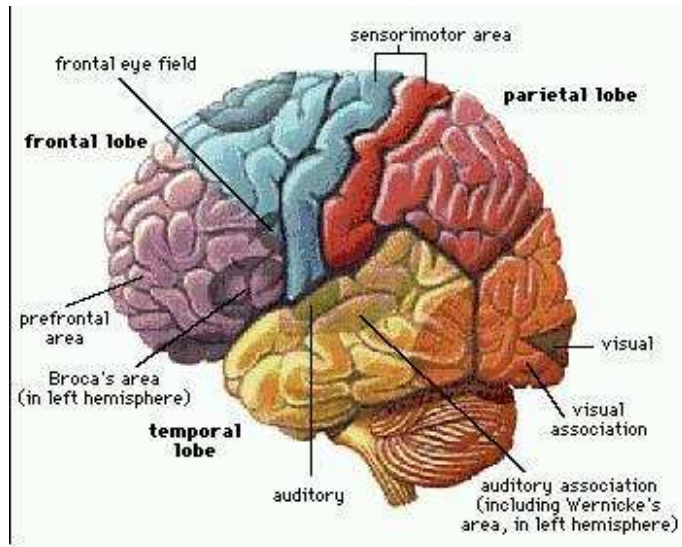
**B** Contrast-Enhancement

**C** Direction-Selectivity



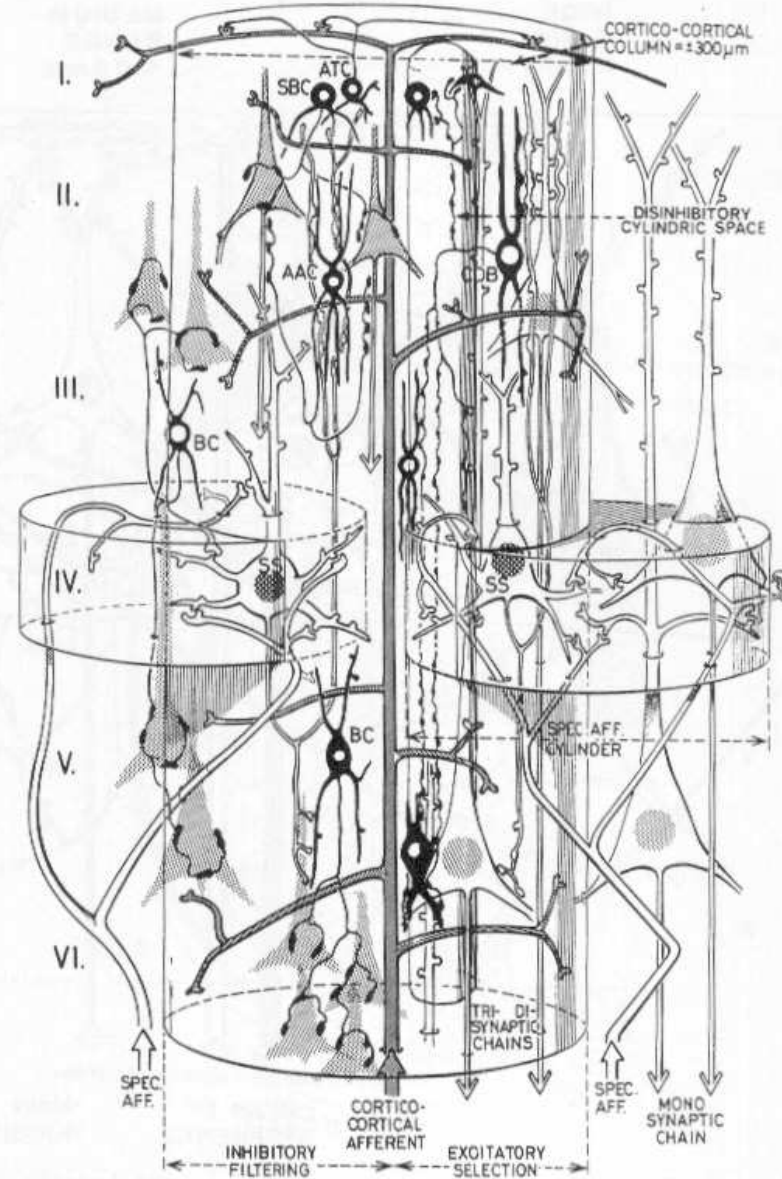


- CPG's are coupled oscillators
- They coordinate complex walking patterns (e.g., animal gaits)
- CPG's for gaits are in the spinal cord.
- Simple commands from the CNS can evoke complex motion patterns.

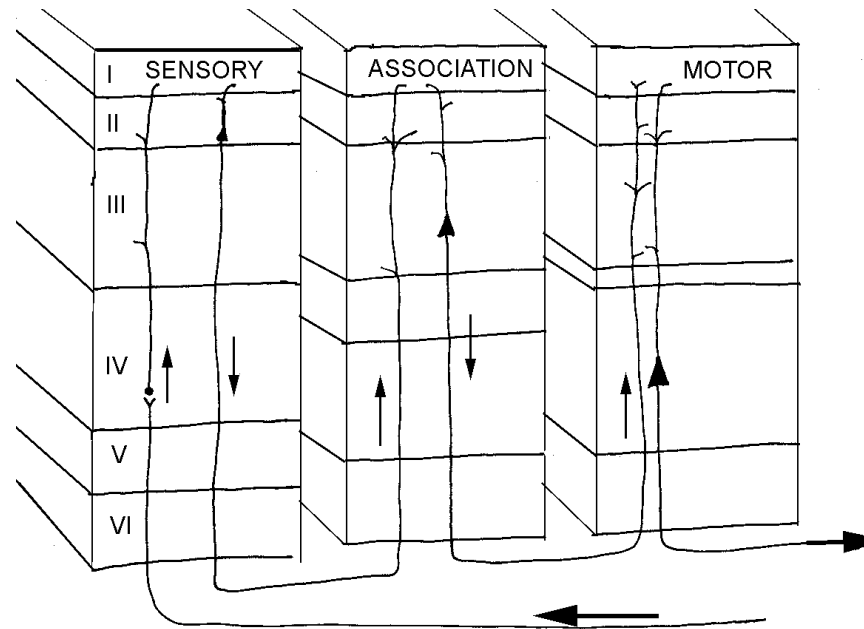


## The cortex

- extracts important signals from the input,
- compares them to stored patterns,
- decides which actions to take.

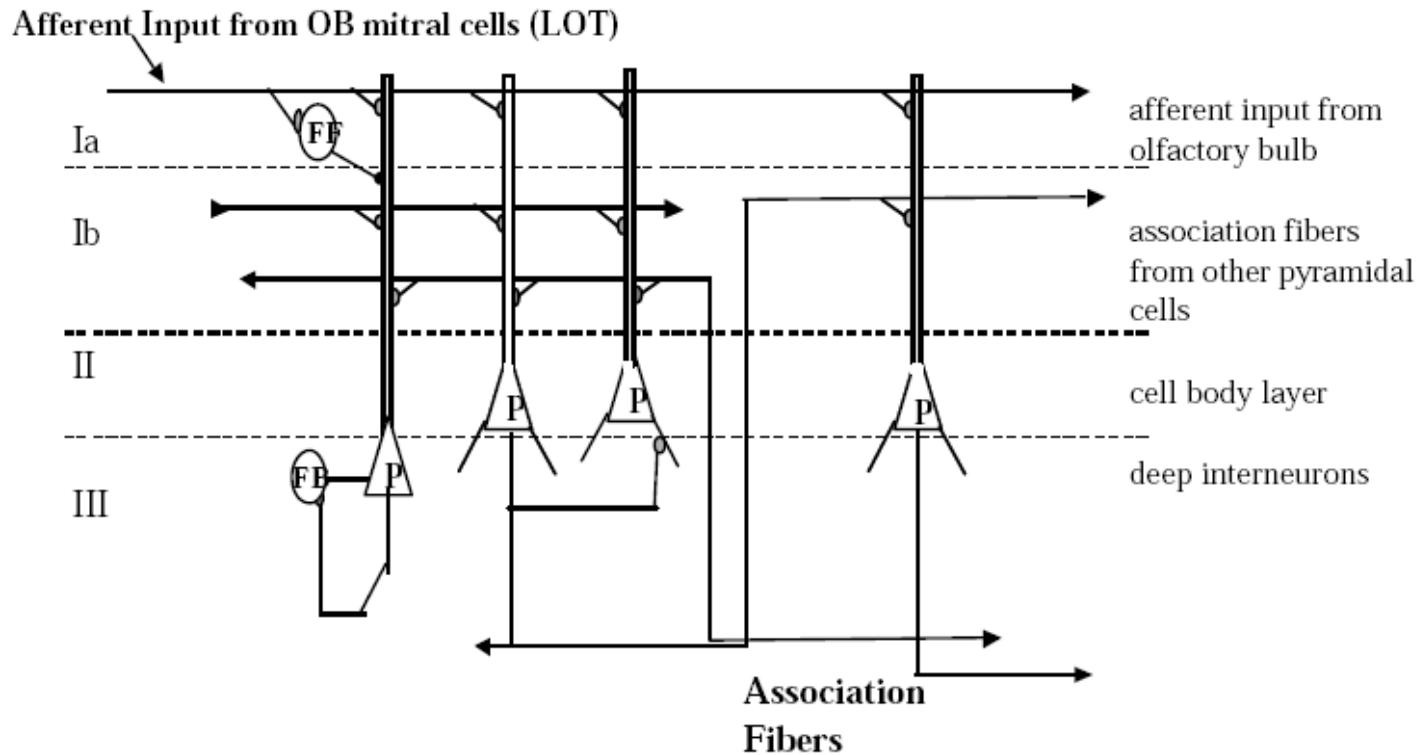


Draft of the cortical column

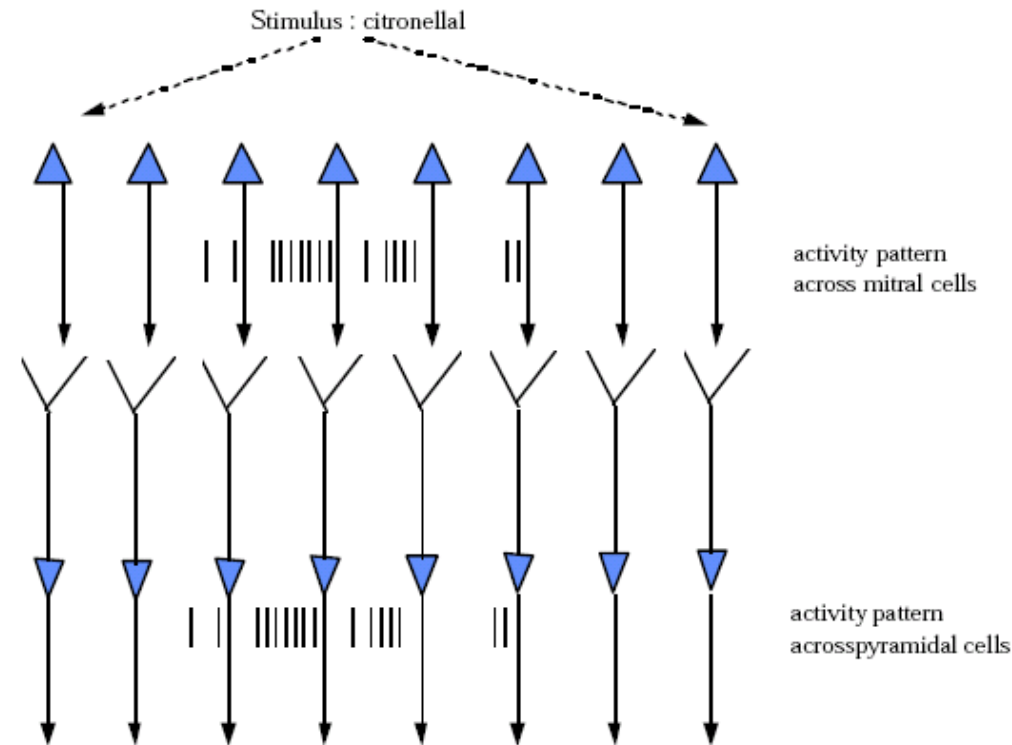


Properties of the cortex:

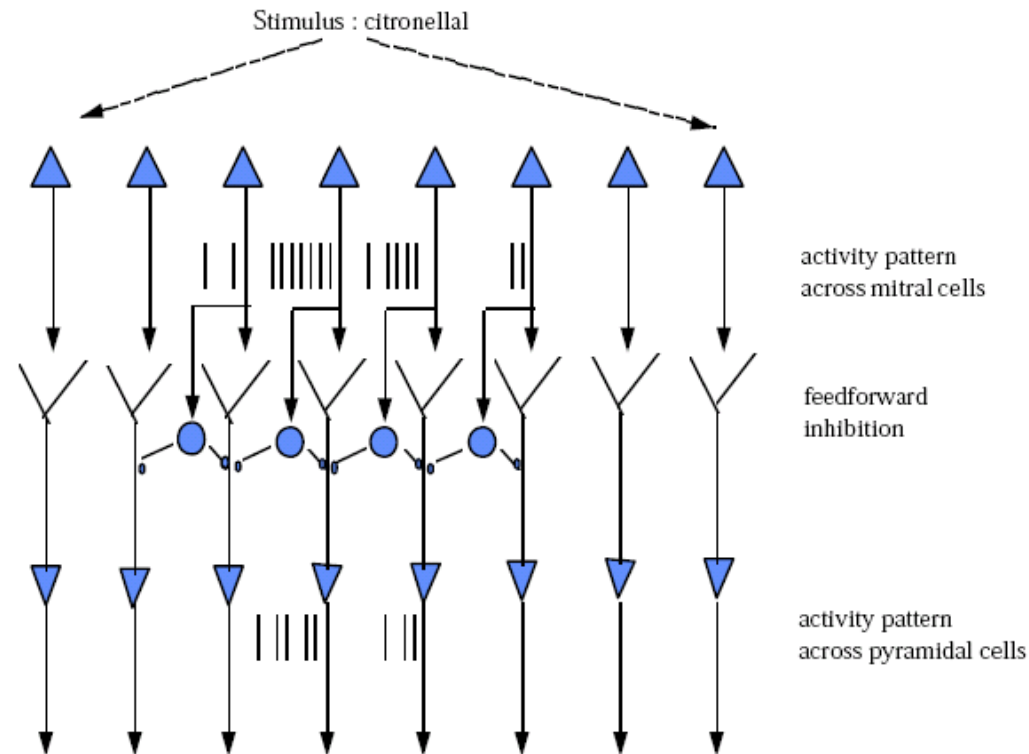
- Divided into 6 (with some exceptions) layers parallel to the surface.
- Important excitatory cells (ca. 85% of the cells in cortex): Pyramidal cells, Spiny Stellate (local interneurons)
- Local connectivity is mainly vertical (columnar architecture).



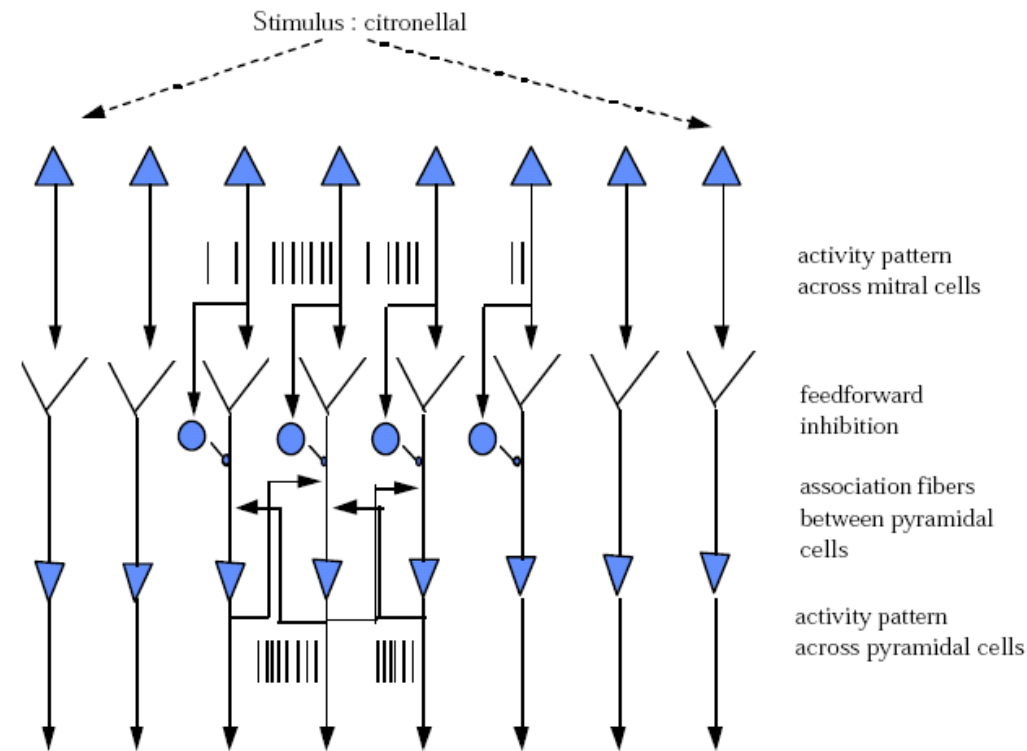
The olfactory cortex has only one layer with cell bodies.



- In the olfactory bulb, odors are coded in the spike timings of so-called mitral cells.
- Afferent inputs from the olfactory bulb project to pyramidal cells.

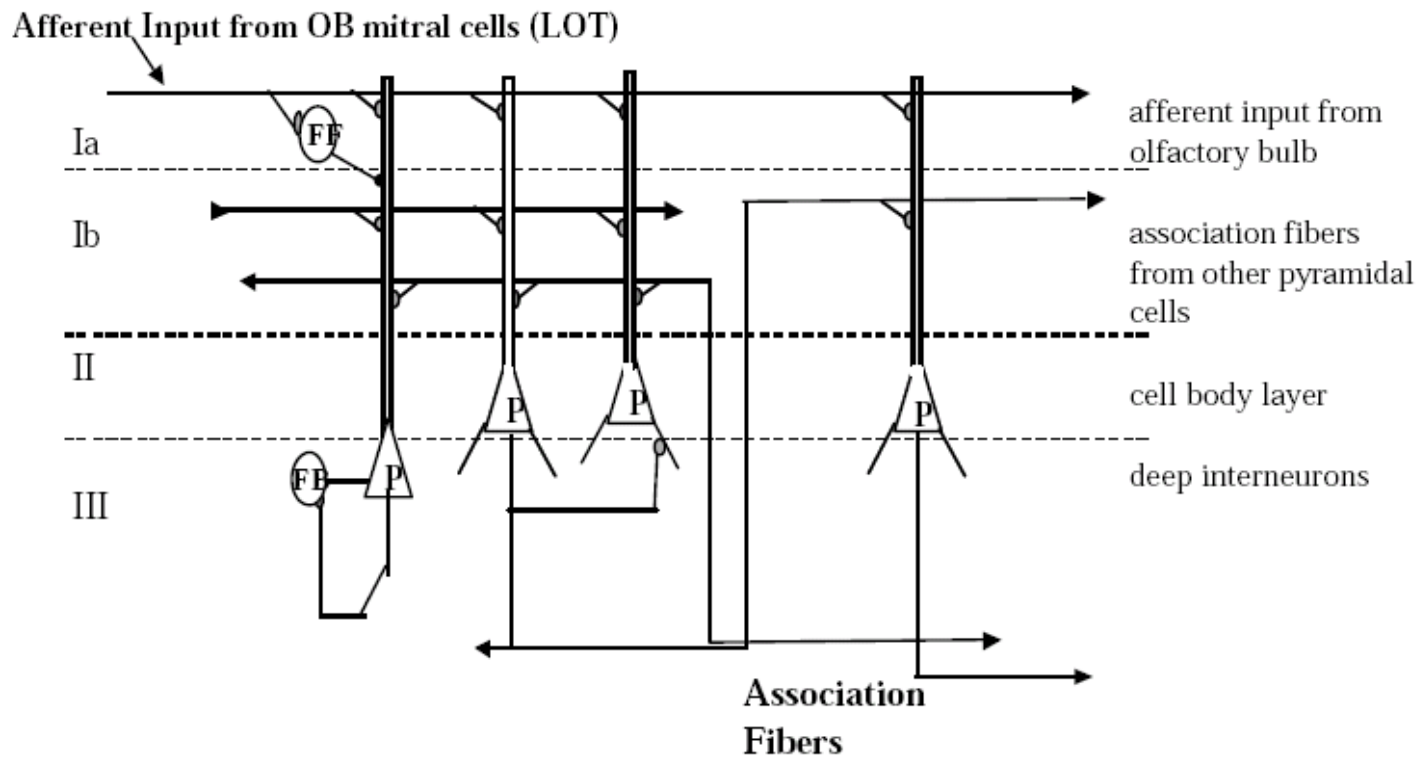


- Local interneurons generate local inhibition.
- This leads to an attenuation of weak stimuli (contrast enhancement).
- When a group of pyramidal neurons mutually inhibiting each other, this can lead to a “winner-take-all” circuit.



- Pyramidal neurons excite other pyramidal neurons via “association fibers”.
- Associations can be learned via Hebbian type learning in these fibers.
- Memory





- A second layer of inhibitory neurons limits the activity of the pyramidal neurons.
- This is called feedback-inhibition.
- Important because of the positive feedback of pyramidal neurons (instability).